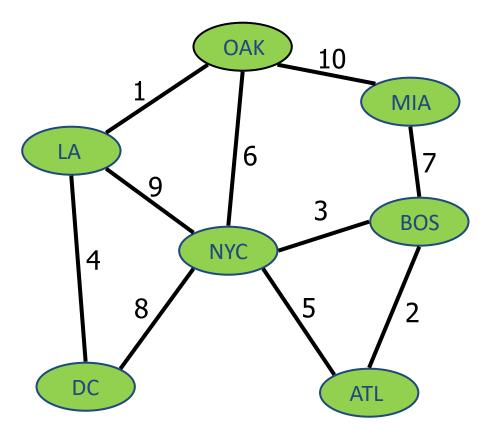


#### Lecture 15

#### Minimum Spanning Trees

CS 161 Design and Analysis of Algorithms
Ioannis Panageas

Definition: We are given an undirected, weighted graph G. A spanning tree of G is a connected acyclic (tree) subgraph of G that includes all the vertices of G (spanning).

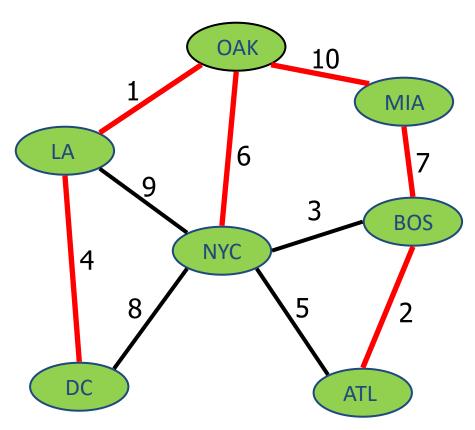


Design and Analysis of Algorithms

Definition: We are given an undirected, weighted graph G. A spanning tree of G is a connected acyclic (tree) subgraph of G that includes all the vertices of G (spanning).

Example:

Total cost 4+1+10+6+7+2 = 30

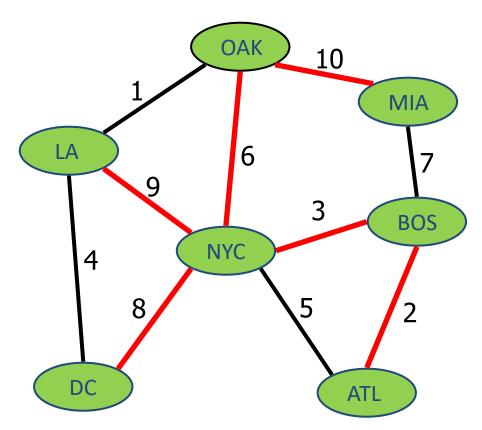


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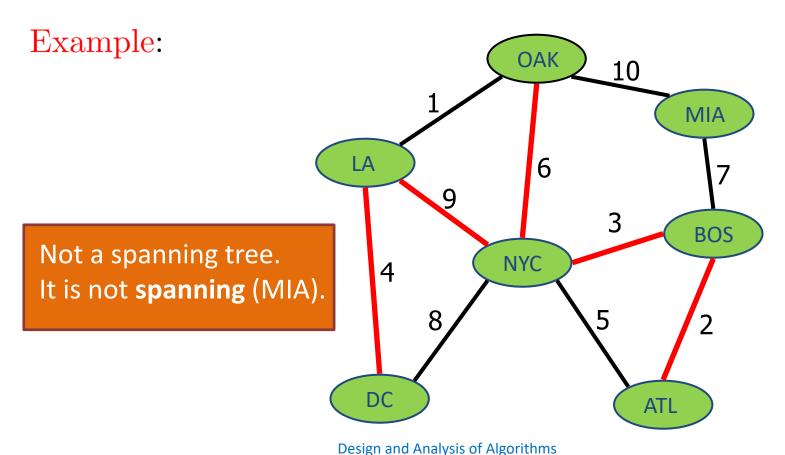
Example:

Total cost 8+9+6+10+3+2 = 38

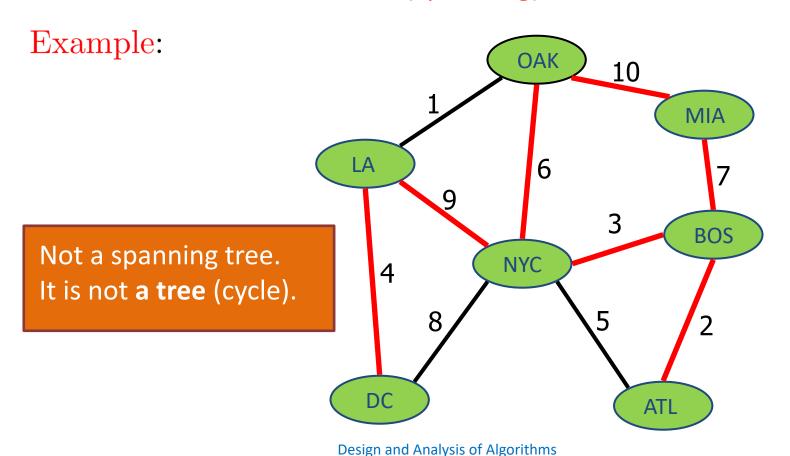


Design and Analysis of Algorithms

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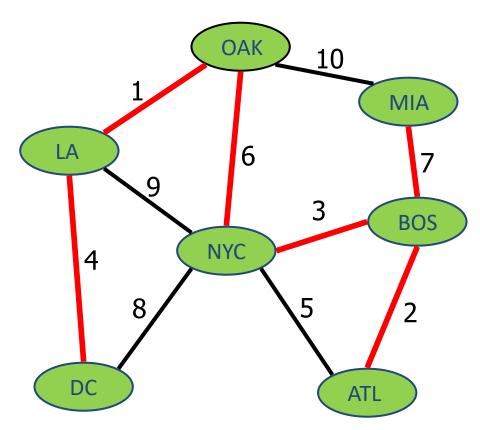
Definition: We are given an undirected, weighted graph G. A spanning tree of G is a connected acyclic (tree) subgraph of G that includes all the vertices of G (spanning).



Problem: We are given an undirected, weighted graph G, find the minimum spanning tree (MST).

#### Example:

Total cost 1+4+6+7+3+2 = 23



Design and Analysis of Algorithms

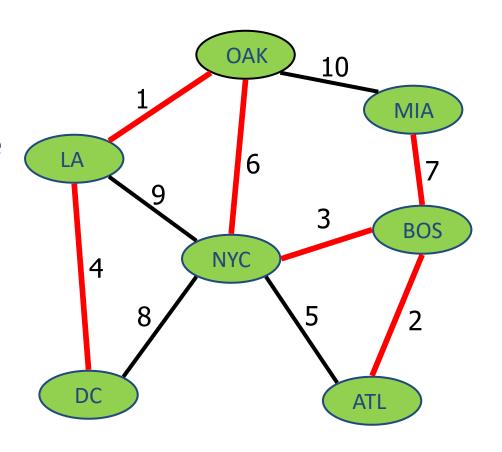
#### Cycle Property

Let *T* be a minimum spanning tree of a weighted graph *G*.

- Let e be an edge of G that is not in T and C let be the cycle formed by e with T.

#### It holds that:

For every edge f of C,  $weight(f) \le weight(e)$ .



#### Cycle Property

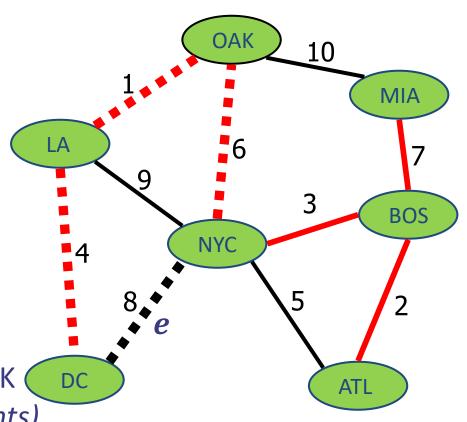
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- Let e be an edge of G that is not in T and C let be the cycle formed by e with T.

#### It holds that:

For every edge f of C,  $weight(f) \le weight(e)$ .

Example 1: Cycle LA, DC, NYC, OAK ( $w(e) = 8 \ge 1, 6, 4 \text{ (rest of weights)}$ 



#### **Cycle Property**

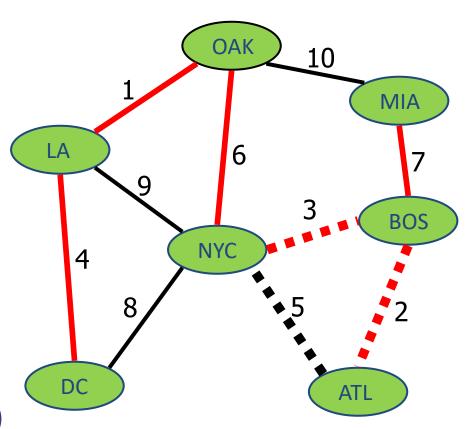
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- Let e be an edge of G that is not in T and C let be the cycle formed by e with T.

#### It holds that:

For every edge f of C,  $weight(f) \le weight(e)$ .

Example 2: Cycle BOS, ATL, NYC  $w(e) = 5 \ge 2, 3$  (rest of weights)



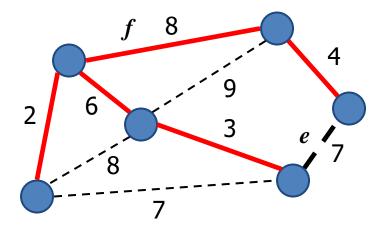
#### **Cycle Property**

For the sake of contradiction:

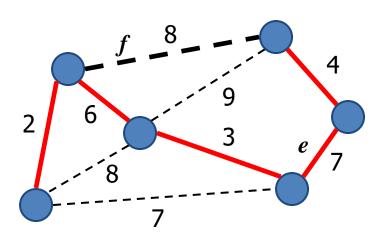
Assume there exist f, e so that

Replacing *f* with *e* yields a better spanning tree

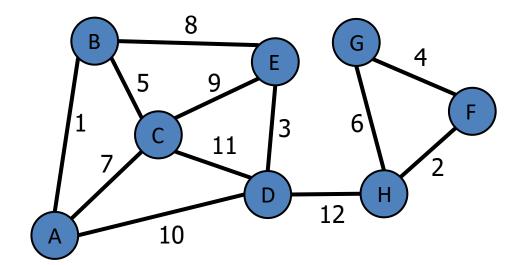
$$\begin{array}{c}
 \text{Total cost} \\
 2+3+4+6+7 = 22
 \end{array}$$



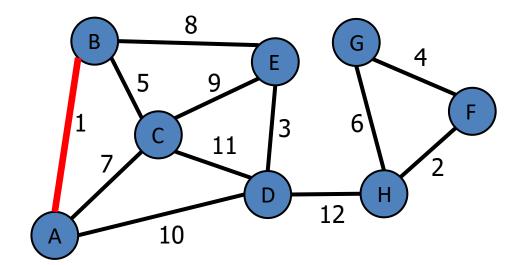
$$\begin{array}{c} \text{Total cost} \\ 2+3+4+6+8 = 23 \end{array}$$



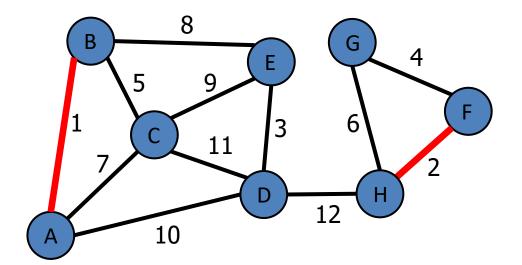
Idea 1: Greedy approach. Consider the edges from smaller weight to larger. Include each edge in the current solution as long as it does not create a cycle, otherwise discard it.



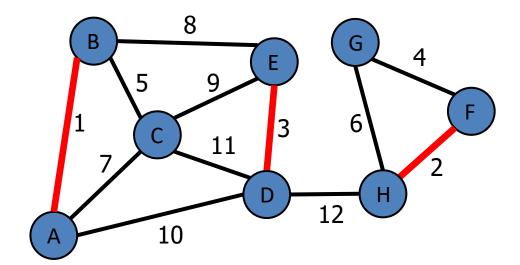
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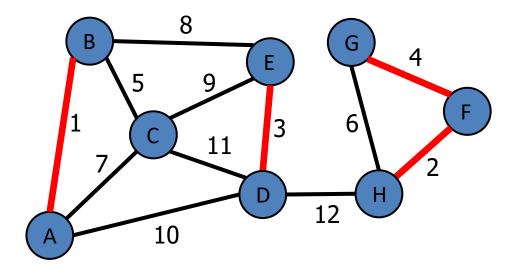
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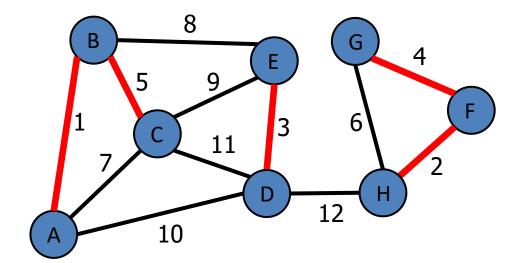
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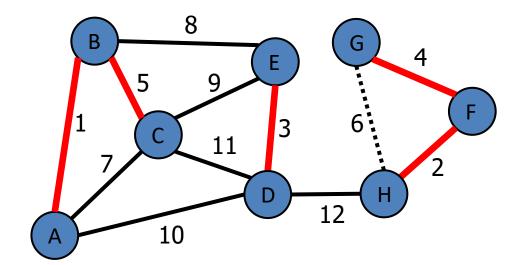
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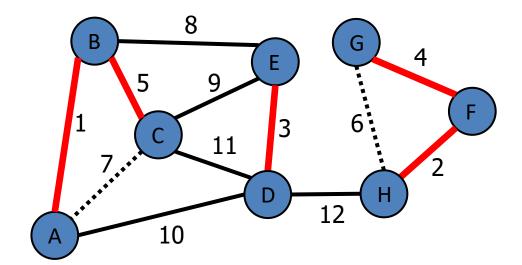
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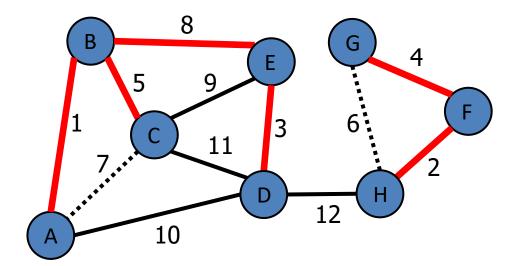
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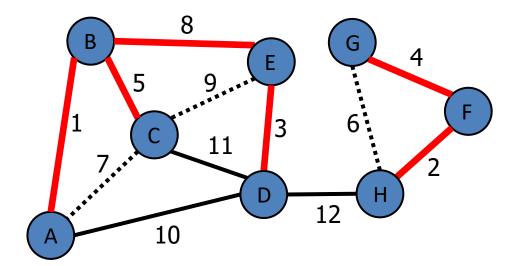
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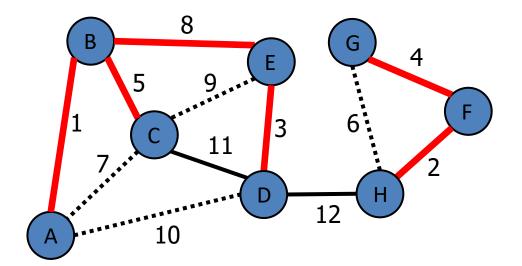
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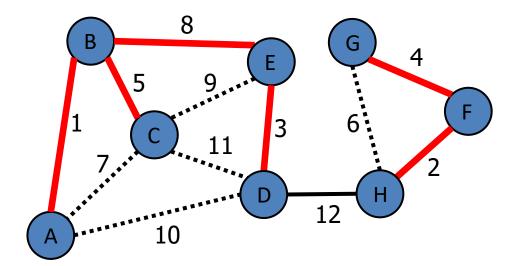
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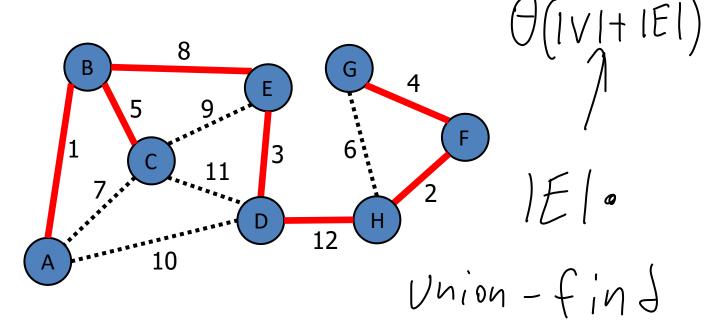
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Idea 1: Greedy approach. Consider the edges from smaller weight to larger. Include each edge in the current solution as long as it does not create a cycle, otherwise discard it.



Total cost 
$$1+2+3+4+5+8+12 = 35$$

Why Kruskal's algo works: General argument. Suppose there is a better solution. Assume the m edges of G are ordered in increasing order of weights, i.e.,  $w_1 \leq w_2 \dots \leq w_m$ . G has also n vertices.

- Let  $x_1, ..., x_{n-1}$  be the weight values of the edges in increasing order of the minimum spanning tree T.
- Let  $y_1, ..., y_{n-1}$  be the weight values of the edges in increasing order of Kruskal's spanning tree T.

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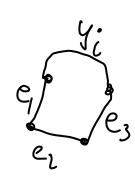
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- Let  $y_1, ..., y_{n-1}$  be the weight values of the edges in increasing order of Kruskal's spanning tree T.
- There is an index i, so that  $y_i < x_i$ . We add edge with value  $y_i$  in T', we create a cycle C.

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  - If  $x_i$  is in C, we remove it and create a spanning tree smaller than T' (contradiction).
  - If  $x_i$  not in C, by cycle property,  $y_i$  is the largest value from edges in C. Kruskal would not have chosen  $y_i$  (contradiction).



Idea 2: Similar to Dijkstra's algorithm. We pick an arbitrary vertex s. We build the **tree** by adding one new vertex at a time. Each vertex v has label d[v] := smallest weight of an edge connecting v to a vertex in the built tree.

#### At each step:

- We add to the current tree the vertex u with the smallest d[u] and the corresponding incident to u edge.
- $\circ$  We update the labels of the vertices adjacent to u.

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$$d[A] = 0$$

$$d[B] = \infty$$

$$d[C] = \infty$$

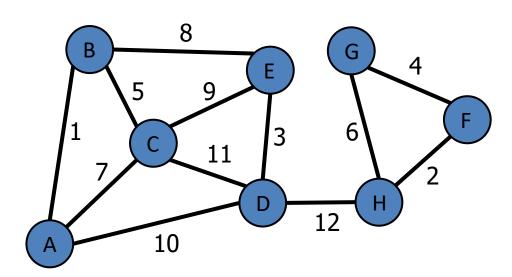
$$d[D] = \infty$$

$$d[E] = \infty$$

$$d[F] = \infty$$

$$d[G] = \infty$$

$$d[H] = \infty$$



- We add to the current tree the vertex u with the smallest d[u] and the corresponding incident to u edge.
- $\circ$  We update the labels of the vertices adjacent to u.

$$d[A] = 0$$

$$d[B] = 1$$

$$d[C] = 7$$

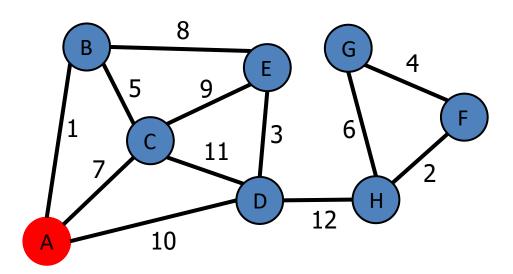
$$d[D] = 10$$

$$d[E] = \infty$$

$$d[F] = \infty$$

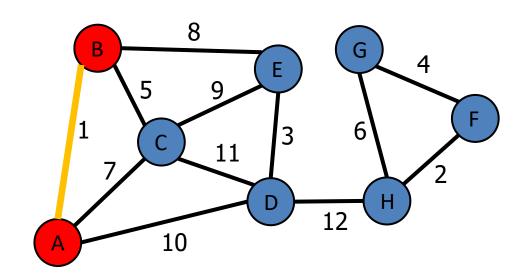
$$d[G] = \infty$$

$$d[H] = \infty$$



- We add to the current tree the vertex u with the smallest d[u] and the corresponding incident to u edge.
- $\circ$  We update the labels of the vertices adjacent to u.

$$d[A] = 0$$
  
 $d[B] = 1$   
 $d[C] = 5$   
 $d[D] = 10$   
 $d[E] = 8$   
 $d[F] = \infty$   
 $d[G] = \infty$   
 $d[H] = \infty$ 



- We add to the current tree the vertex u with the smallest d[u] and the corresponding incident to u edge.
- $\circ$  We update the labels of the vertices adjacent to u.

$$d[A] = 0$$

$$d[B] = 1$$

$$d[C] = 5$$

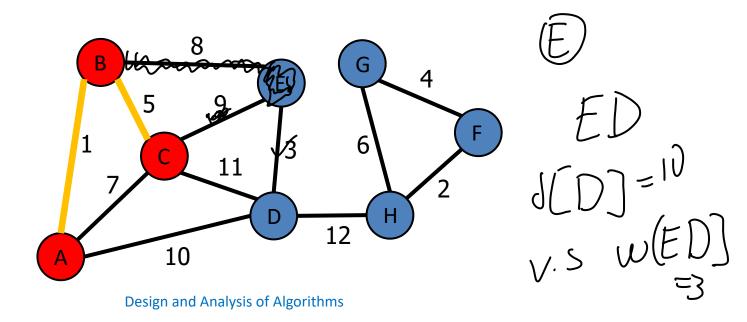
$$d[D] = 10$$

$$d[E] = 8$$

$$d[F] = \infty$$

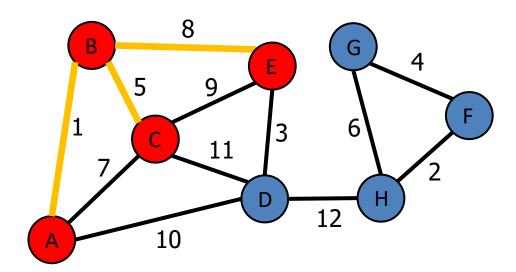
$$d[G] = \infty$$

$$d[H] = \infty$$



- We add to the current tree the vertex u with the smallest d[u] and the corresponding incident to u edge.
- $\circ$  We update the labels of the vertices adjacent to u.

$$d[A] = 0$$
 $d[B] = 1$ 
 $d[C] = 5$ 
 $d[D] = 3$ 
 $d[E] = 8$ 
 $d[F] = \infty$ 
 $d[G] = \infty$ 
 $d[H] = \infty$ 



- We add to the current tree the vertex u with the smallest d[u] and the corresponding incident to u edge.
- $\circ$  We update the labels of the vertices adjacent to u.

$$d[A] = 0$$

$$d[B] = 1$$

$$d[C] = 5$$

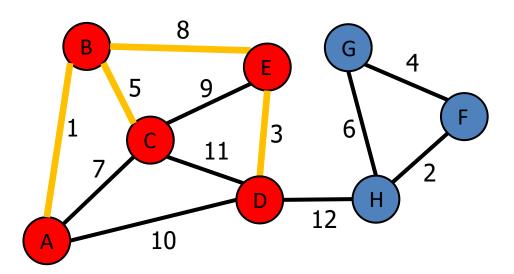
$$d[D] = 3$$

$$d[E] = 8$$

$$d[F] = \infty$$

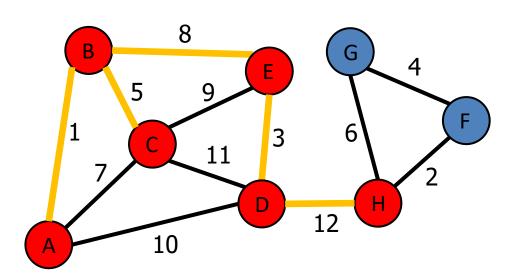
$$d[G] = \infty$$

$$d[H] = 12$$



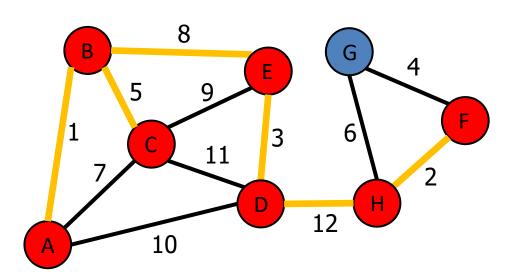
- We add to the current tree the vertex u with the smallest d[u] and the corresponding incident to u edge.
- $\circ$  We update the labels of the vertices adjacent to u.

$$d[A] = 0$$
  
 $d[B] = 1$   
 $d[C] = 5$   
 $d[D] = 3$   
 $d[E] = 8$   
 $d[F] = 2$   
 $d[G] = 6$   
 $d[H] = 12$ 



- We add to the current tree the vertex u with the smallest d[u] and the corresponding incident to u edge.
- $\circ$  We update the labels of the vertices adjacent to u.

$$d[A] = 0$$
  
 $d[B] = 1$   
 $d[C] = 5$   
 $d[D] = 3$   
 $d[E] = 8$   
 $d[F] = 2$   
 $d[G]=4$   
 $d[H] = 12$ 



Prim's Algorithm for MSTs Dijkstra's Algorithm. We pick an arbitrary vertex s.

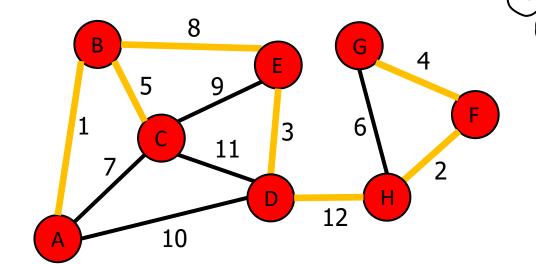
At each step:

Prim: d[V] vs  $\omega(u,V)$ 

We add to the current tree the vertex u with the smallest d[u]and the corresponding incident to u edge.

We update the labels of the vertices adjacent to u.

d[A] = 0d[B] = 1d[C] = 5d[D] = 3d[E] = 8d[F] = 2d[H] = 12



#### Pseudocode:

Pick any vertex v of G

 $D[v] \leftarrow 0$ 

for each vertex  $u \neq v$  do

 $D[u] \leftarrow +\infty$ 

Initialize  $T \leftarrow \emptyset$ .

**Starting vertex** 

**Initialization** 

Initialize a priority queue Q with an item ((u, null), D[u]) for each vertex u, where (u, null) is the element and D[u] is the key.

while Q is not empty do

 $(u,e) \leftarrow Q.\mathsf{removeMin}()$ 

Add vertex u and edge e to T.

for each vertex z adjacent to u such that z is in Q do // perform the relaxation procedure on edge (u, z)

if w((u,z)) < D[z] then

 $D[z] \leftarrow w((u,z))$ 

Change to (z, (u, z)) the element of vertex z in Q.

Change to D[z] the key of vertex z in Q.

**return** the tree T



Relaxation

#### Pseudocode:

```
Pick any vertex v of G
                                                              Starting vertex
D[v] \leftarrow 0
for each vertex u \neq v do
    D[u] \leftarrow +\infty
                                                                     Initialization
Initialize T \leftarrow \emptyset.
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while Q is not empty do
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         // perform the relaxation procedure on edge (u, z)
          if w((u,z)) < D[z] then
              D[z] \leftarrow w((u,z))
```

Relaxation

**return** the tree T

Running time: If extractmin in  $\Theta(|V|)$ , update in  $\Theta(1)$  then  $|V|^2 + |E|$ .

Change to (z, (u, z)) the element of vertex z in Q.

Change to D[z] the key of vertex z in Q.

#### Pseudocode:

Pick any vertex v of G  $D[v] \leftarrow 0$  for each vertex  $u \neq v$  do  $D[u] \leftarrow +\infty$  Initialize  $T \leftarrow \emptyset$ .

**Starting vertex** 

**Initialization** 

Initialize a priority queue Q with an item ((u, null), D[u]) for each vertex u, where (u, null) is the element and D[u] is the key.

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 ${f for}$  each vertex z adjacent to u such that z is in Q  ${f do}$ 

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return the tree T

Running time: If extractmin in  $\Theta(|V|)$ , update in  $\Theta(1)$ 

Relaxation

 $\Theta(|V|^2)$ 

#### Pseudocode:

```
Pick any vertex v of G
                                                             Starting vertex
D[v] \leftarrow 0
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              Change to (z, (u, z)) the element of vertex z in Q.
```

Change to D[z] the key of vertex z in Q.

Relaxation

**return** the tree T

Running time: If extractmin, update in  $\Theta(\log |V|)$  then  $|E| \log |V|$ .