

Lecture 6 Av. case analysis of quick sort, divide and conquer, mergesort

CS 161 Design and Analysis of Algorithms
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Pseudocode for Quicksort

```
def quickSort(A,first,last):
    if first < last:
        splitpoint = split(A,first,last)
        quickSort(A,first,splitpoint-1)
        quickSort(A,splitpoint+1,last)</pre>
```



The split step

Loop invariants:

- ► A[first+1..splitpoint] contains keys < x.
- ▶ A[splitpoint+1..k-1] contains keys $\geq x$.
- ► A[k..last] contains unprocessed keys.

The split step

At start:



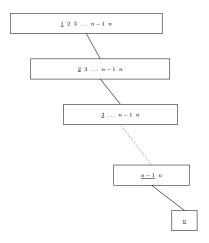
In middle:



At end:

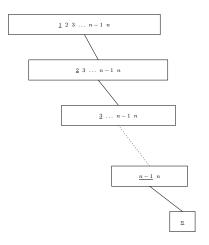


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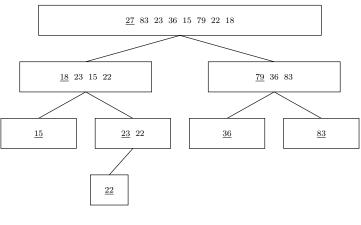
Our approach:

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- 4. Use this to compute the expected number of comparisons performed by Quicksort.



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- ▶ 23 and 22 (both statements true)
- ▶ 36 and 83 (both statements false)

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Define indicator random variables $\{X_{i,j} : 1 \le i < j \le n\}$

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3. The expected value of $X_{i,j}$ is:

$$E(X_{i,j}) = P_{i,j} = \frac{2}{j-i+1}$$

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So the average time for Quicksort is $O(n \lg n)$.

Divide and Conquer

Divide and conquer paradigm

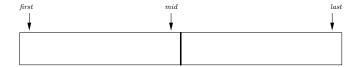
- 1. Split problem into subproblem(s)
- 2. Solve each subproblem (usually via recursive call)
- Combine solution of subproblem(s) into solution of original problem

We will discuss two sorting algorithms based on this paradigm:

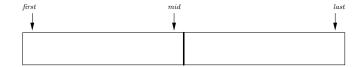
- Quicksort (done)
- Mergesort

${\sf MergeSort}$

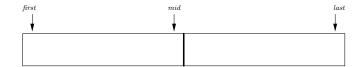
► Split array into two equal subarrays



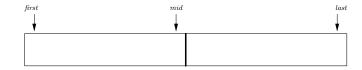
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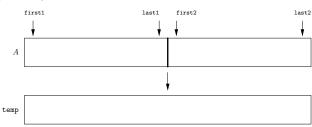
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- Merge two sorted subarrays

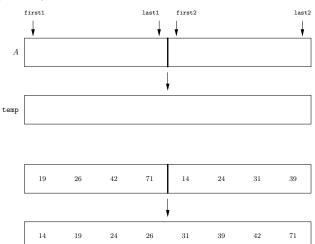


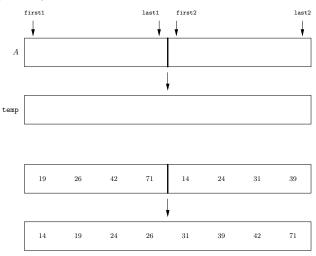
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```
def mergeSort(A,first,last):
    if first < last:
        mid = [(first + last)/2]
        mergeSort(A,first,mid)
        mergeSort(A,mid+1,last)
        merge(A,first,mid,mid+1,last)</pre>
```







Merging two lists of total size n requires at most n-1 comparisons.

Code for the merge step

```
def merge(A,first1,last1,first2,last2):
    index1 = first1; index2 = first2; tempIndex = 0
   // Merge into temp array until one input array is exhausted
    while (index1 <= last1) and (index2 <= last2)
        if A[index1] <= A[index2]:</pre>
            temp[tempIndex++] = A[index1++]
        else:
            temp[tempIndex++] = A[index2++]
   // Copy appropriate trailer portion
    while (index1 <= last1): temp[tempIndex++] = A[index1++]</pre>
    while (index2 <= last2): temp[tempIndex++] = A[index2++]</pre>
   // Copy temp array back to A array
    tempIndex = 0; index = first1
    while (index <= last2): A[index++] = temp[tempIndex++]</pre>
```

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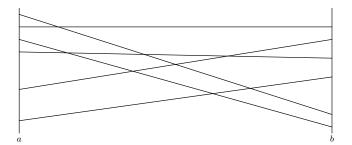
The exact solution of this recurrence equation is

$$T(n) = n\lceil \lg n \rceil - 2^{\lceil \lg n \rceil} + 1$$

▶ Input: *n* lines in the plane, none of which are vertical; two vertical lines x = a and x = b (with a < b).

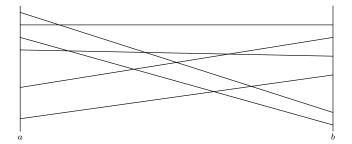
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Example: n = 6



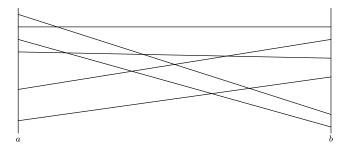
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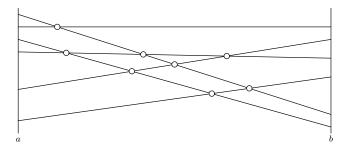
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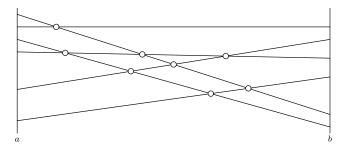
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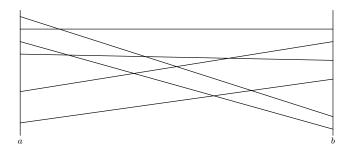


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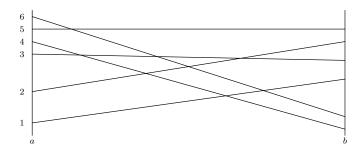
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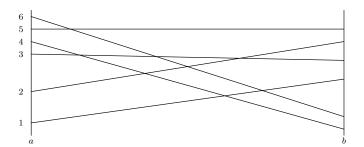
Checking every pair of lines takes $\Theta(n^2)$ time. We can do better.



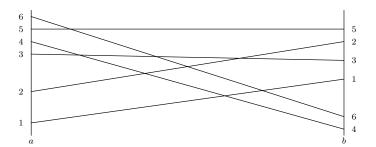
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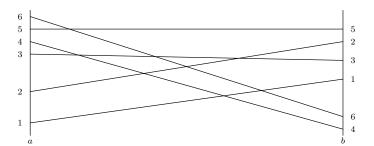
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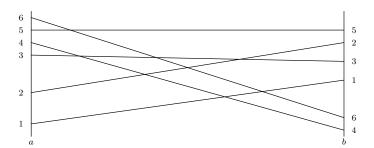


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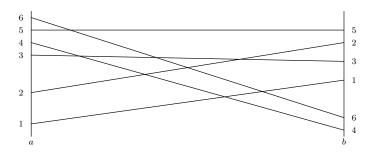
Geometrical Application: Counting line intersections

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So the problem reduces to counting/reporting inversions.

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Example: The list [18, 29, 12, 15, 32, 10] has 9 inversions:

(18, 12), (18, 15), (18, 10), (29, 12), (29, 15), (29, 10), (12, 10), (15, 10), (32, 10)

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Example: The list [18, 29, 12, 15, 32, 10] has 9 inversions: (18, 12), (18, 15), (18, 10), (29, 12), (29, 15), (29, 10), (12, 10), (15, 10), (32, 10)

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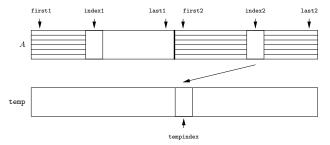
In principle, we can use any sorting algorithm to count inversions. Mergesort works particularly nicely.

Inversion Counting with MergeSort

In Mergesort, the only time we rearrange data is during the merge step.

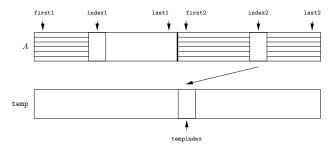
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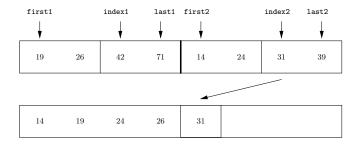


The number of inversions removed is:

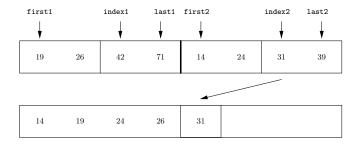
$$last1 - index1 + 1$$

Example

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2 inversions removed: (42, 31) and (71, 31)

Pseudocode for the merge step with inversion counting

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```
def merge(A,first1,last1,first2,last2):
    index1 = first1; index2 = first2; tempIndex = 0
    invCount = 0
   // Merge into temp array until one input array is exhausted
    while (index1 <= last1) and (index2 <= last2)</pre>
        if A[index1] <= A[index2]:
            temp[tempIndex++] = A[index1++]
        else:
            temp[tempIndex++] = A[index2++]
            invCount += last1 - index1 + 1;
   // Copy appropriate trailer portion
    while (index1 <= last1): temp[tempIndex++] = A[index1++]</pre>
    while (index2 <= last2): temp[tempIndex++] = A[index2++]</pre>
   // Copy temp array back to A array
    tempIndex = 0; index = first1
    while (index <= last2): A[index++] = temp[tempIndex++]</pre>
    return invCount
```

Pseudocode for MergeSort with inversion counting

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```
def mergeSort(A,first,last):
    invCount = 0
    if first < last:
        mid = [(first + last)/2]
        invCount += mergeSort(A,first,mid)
        invCount += mergeSort(A,mid+1,last)
        invCount += merge(A,first,mid,mid+1,last)
    return invCount</pre>
```

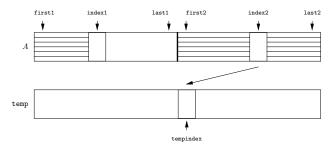
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Running time is the same as standard mergeSort: $O(n \log n)$

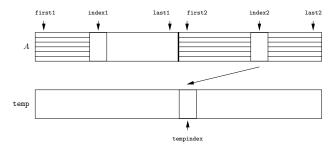
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 $(A[index1], A[index2]), (A[index1+1], A[index2]), \dots, (A[last1], A[index2]).$

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$$(A[index1], A[index2]), (A[index1+1], A[index2]), ..., (A[last1], A[index2]).$$

The extra work to do the reporting is proportional to the number of inversions reported.

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The reporting algorithm is an example of an output-sensitive algorithm. The performance of the algorithm depends on the size of the output as well as the size of the input.