# L06 Potential and Congestion Games

CS 280 Algorithmic Game Theory Ioannis Panageas

**Definition** (Potential Games). A normal form game is specified by

- *set of n players*  $[n] = \{1, ..., n\}$
- For each player i a set of strategies/actions  $S_i$  and a utility  $u_i : \times_{i=1}^n S_j \to \mathbb{R}$  denoting the payoff of i.
- set of strategy profiles  $S = S_1 \times ... \times S_n$ .
- There exists a potential function  $\Phi: S \to \mathbb{R}$  so that for all agents i and  $s_i, s_i'$

$$\Phi(s_i, s_{-i}) - \Phi(s_i', s_{-i}) = u_i(s_i, s_{-i}) - u_i(s_i', s_{-i}).$$

**Definition** (Potential Games). A normal form game is specified by

- *set of n players*  $[n] = \{1, ..., n\}$
- For each player i a set of strategies/actions  $S_i$  and a utility  $u_i : \times_{j=1}^n S_j \to \mathbb{R}$  denoting the payoff of i.
- set of strategy profiles  $S = S_1 \times ... \times S_n$ .
- There exists a potential function  $\Phi: S \to \mathbb{R}$  so that for all agents i and  $s_i, s_i'$

$$\Phi(s_i, s_{-i}) - \Phi(s_i', s_{-i}) = u_i(s_i, s_{-i}) - u_i(s_i', s_{-i}).$$

#### Example (Battle of sexes).

5, 2	-1,-2	$\rightarrow$	4	0
-5, -4	1,4		-6	2

Intro to AGT

**Definition** (Potential Games). A normal form game is specified by

- *set of n pll* Weighted Potential Games:
- For each p  $u_i: \times_{j=1}^n \{ \Phi(s_i, s_{-i}) \Phi(s_i', s_{-i}) = w_i \cdot (u_i(s_i, s_{-i}) u_i(s_i', s_{-i})) \}$ where  $w_i > 0$ .
- set of strat
- There exists a potential function  $\Phi: S \to \mathbb{R}$  so that for all agents i and  $s_i, s_i'$

$$\Phi(s_i, s_{-i}) - \Phi(s_i', s_{-i}) = u_i(s_i, s_{-i}) - u_i(s_i', s_{-i}).$$

Example (Battle of sexes).

5, 2	-1,-2	$\rightarrow$	4	0
-5, -4	1,4		-6	2

Intro to AGT

Question: What is interesting about these games?

Answer: A pure Nash equilibrium always exists!

**Lemma.** Let G be a potential game. It has a pure Nash equilibrium.

Question: What is interesting about these games?

Answer: A pure Nash equilibrium always exists!

**Lemma.** Let G be a potential game. It has a pure Nash equilibrium.

*Proof.* Let  $s^*$  a pure strategy profile that maximizes  $\Phi$ . Then  $s^*$  is a Nash equilibrium.

Question: What is interesting about these games?

Answer: A pure Nash equilibrium always exists!

**Lemma.** Let G be a potential game. It has a pure Nash equilibrium.

*Proof.* Let  $s^*$  a pure strategy profile that maximizes  $\Phi$ . Then  $s^*$  is a Nash equilibrium. Assuming not, there is an agent i and strategy  $s'_i$  so that

$$u_i(s_i^*, s_{-i}^*) < u_i(s_i', s_{-i}^*).$$

Question: What is interesting about these games?

Answer: A pure Nash equilibrium always exists!

**Lemma.** Let G be a potential game. It has a pure Nash equilibrium.

*Proof.* Let  $s^*$  a pure strategy profile that maximizes  $\Phi$ . Then  $s^*$  is a Nash equilibrium. Assuming not, there is an agent i and strategy  $s'_i$  so that

$$u_i(s_i^*, s_{-i}^*) < u_i(s_i', s_{-i}^*).$$

$$\Phi(s_i^*, s_{-i}^*) - \Phi(s_i', s_{-i}^*) = u_i(s_i^*, s_{-i}^*) - u_i(s_i', s_{-i}^*) < 0.$$

Contradiction!

#### Algorithm (Greedy).

- 1. Initialize  $s^{(0)}$  arbitrarily.
- 2. Loop
- **Find** agent  $i, s'_{i}$  so that  $u_{i}(s'_{i}, s^{(t)}_{-i}) > u_{i}(s^{(t)})$
- 4. Set  $s^{(t+1)} = (s'_i, s^{(t+1)}_{-i}).$ 5. t = t+1
- If no agent exists STOP

**Lemma.** The algorithm above reaches a pure Nash equilibrium.

#### Algorithm (Greedy).

- 1. Initialize  $s^{(0)}$  arbitrarily.
- 2. Loop
- **Find** agent  $i, s'_{i}$  so that  $u_{i}(s'_{i}, s^{(t)}_{-i}) > u_{i}(s^{(t)})$
- 4. Set  $s^{(t+1)} = (s'_i, s^{(t+1)}_{-i}).$ 5. t = t+1
- If no agent exists STOP

**Lemma.** The algorithm above reaches a pure Nash equilibrium.

*Proof.* Construct a directed graph with |S| vertices and an edge from  $s \to s'$  if strategy profiles s, s' differ in one agent only, say i and  $u_i(s') > u_i(s)$ .

• The graph has no cycles.

#### Algorithm (Greedy).

- 1. Initialize  $s^{(0)}$  arbitrarily.
- 2. Loop
- **Find** agent  $i, s'_{i}$  so that  $u_{i}(s'_{i}, s^{(t)}_{-i}) > u_{i}(s^{(t)})$
- 4. Set  $s^{(t+1)} = (s'_i, s^{(t+1)}_{-i}).$ 5. t = t+1
- If no agent exists STOP

**Lemma.** The algorithm above reaches a pure Nash equilibrium.

*Proof.* Construct a directed graph with |S| vertices and an edge from  $s \to s'$  if strategy profiles s, s' differ in one agent only, say i and  $u_i(s') > u_i(s)$ .

- The graph has no cycles.
- The algorithm reaches a sink vertex (no outgoing edges).

## **Congestion Games**

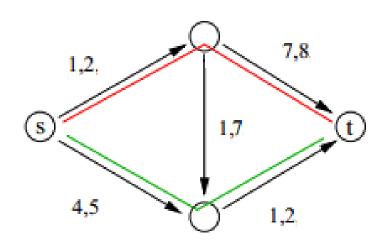
#### A congestion game is defined by:

- n set of players.
- E set of edges/facilities/ bins.
- $S_i \subset 2^E$  the set of strategies of player i.
- $c_e: \{1, ..., n\} \to \mathbb{R}^+ \text{ cost function of edge } e.$

For any 
$$s = (s_1, ..., s_n)$$

- $l_e(s)$  number of players (load) that use edge e.
- $c_i(s) = \sum_{e \in s_i} c_e(l_e)$  the cost function of player i.

### **Congestion Games**



For this game:

 $n = \{1, 2\}$  (red, green) E are the edges of the network.  $S_i$  is all s - t paths.  $c_e$  on edges.

Remark: Defined by Rosenthal in 1973. Capture atomic routing games!

**Theorem** (Rosenthal 73'). Congestion Games are potential games.

*Proof.* We need to come up with a potential function!

**Theorem** (Rosenthal 73'). Congestion Games are potential games.

*Proof.* We need to come up with a potential function!

Consider the function 
$$\Phi(s) = \sum_{e \in E} \sum_{j=1}^{l_e(s)} c_e(j)$$
.

**Theorem** (Rosenthal 73'). Congestion Games are potential games.

*Proof.* We need to come up with a potential function!

Consider the function  $\Phi(s) = \sum_{e \in E} \sum_{j=1}^{l_e(s)} c_e(j)$ .

Fix agent i strategy s, s', where s, s' differ on agent's i strategy.

• 
$$\Phi(s) = \sum_{e \in s \cap s'} \sum_{j=1}^{l_e(s)} c_e(j) + \sum_{e \in s \setminus s'} \sum_{j=1}^{l_e(s)} c_e(j) + \sum_{e \in s' \setminus s} \sum_{j=1}^{l_e(s)} c_e(j) + \sum_{e \in s' \setminus s} \sum_{j=1}^{l_e(s)} c_e(j) + \sum_{e \in s' \setminus s'} \sum_{j=1}$$

• 
$$\Phi(s') = \sum_{e \in s \cap s'} \sum_{j=1}^{l_e(s')} c_e(j) + \sum_{e \in s' \setminus s} \sum_{j=1}^{l_e(s')} c_e(j) + \sum_{e \in s \setminus s'} \sum_{e \in s'} \sum_{j=1}^{l_e(s')} c_e(j) + \sum_{e \in s \setminus s'} \sum_{e \in s'} \sum_{e \in$$

#### Missing terms

$$+ \sum_{e \notin s,s'} \sum_{j=1}^{l_e(s)} c_e(j) + \sum_{e \notin s,s'} \sum_{j=1}^{l_e(s')} c_e(j)$$

**Theorem** (Rosenthal 73'). Congestion Games are potential games.

*Proof.* We need to come up with a potential function!

Consider the function  $\Phi(s) = \sum_{e \in E} \sum_{j=1}^{l_e(s)} c_e(j)$ .

Fix agent i strategy s, s', where s, s' differ on agent's i strategy.

• 
$$\Phi(s) = \sum_{e \in s \cap s'} \sum_{j=1}^{l_e(s)} c_e(j) + \sum_{e \in s \setminus s'} \sum_{j=1}^{l_e(s)} c_e(j) + \sum_{e \in s' \setminus s} \sum_{j=1}^{l_e(s)} c_e(j) +$$
•  $\Phi(s') = \sum_{e \in s \cap s'} \sum_{j=1}^{l_e(s')} c_e(j) + \sum_{e \in s' \setminus s} \sum_{j=1}^{l_e(s')} c_e(j) + \sum_{e \in s \setminus s'} \sum_{j=1}^{l_e(s')} c_e(j) +$ 

Same load

$$l_e(s) = l_e(s') + 1$$
  $l_e(s) = l_e(s') - 1$ 

Missing terms (same load)

$$+ \sum_{e \notin s,s'} \sum_{j=1}^{l_e(s)} c_e(j) + \sum_{e \notin s,s'} \sum_{j=1}^{l_e(s')} c_e(j)$$

**Theorem** (Rosenthal 73'). Congestion Games are potential games.

$$\Phi(s) - \Phi(s') = \sum_{e \in s \setminus s'} c_e(l_e(s)) - \sum_{e \in s' \setminus s} c_e(l_e(s'))$$

• 
$$\Phi(s) = \sum_{e \in s \cap s'} \sum_{j=1}^{l_e(s)} c_e(j) + \sum_{e \in s \setminus s'} \sum_{j=1}^{l_e(s)} c_e(j) + \sum_{e \in s' \setminus s} \sum_{j=1}^{l_e(s)} c_e(j) + \sum_{e \in s' \setminus s} \sum_{j=1}^{l_e(s')} c_e(j) + \sum_{e \in s \cap s'} \sum_{j=1}^{l_e(s')} c_e(j) + \sum_{e \in s' \setminus s} \sum_{j=1}^{l_e(s')} c_e(j) + \sum_{e \in s \setminus s'} \sum_{j=1}^{l_e(s')} c_e(j) + \sum_{e \in s'} \sum_{j=1}^{l_e(s')} c_e(j) + \sum_{e \in s'} \sum_{j=1}^{l_e(s'$$

Same load

$$l_e(s) = l_e(s') + 1$$
  $l_e(s) = l_e(s') - 1$ 

Missing terms (same load)

$$+ \sum_{e \notin s,s'} \sum_{j=1}^{l_e(s)} c_e(j) + \sum_{e \notin s,s'} \sum_{j=1}^{l_e(s')} c_e(j)$$

Proof cont. 
$$\Phi(s) - \Phi(s') = \sum_{e \in s \setminus s'} c_e(l_e(s)) - \sum_{e \in s' \setminus s} c_e(l_e(s'))$$

• 
$$u_i(s) = \sum_{e \in s \cap s'} c_e(l_e(s)) + \sum_{e \in s \setminus s'} c_e(l_e(s)).$$

• 
$$u_i(s) = \sum_{e \in s \cap s'} c_e(l_e(s)) + \sum_{e \in s \setminus s'} c_e(l_e(s)).$$
  
•  $u_i(s') = \sum_{e \in s \cap s'} c_e(l_e(s')) + \sum_{e \in s' \setminus s} c_e(l_e(s')).$ 

Same load

Proof cont. 
$$\Phi(s) - \Phi(s') = \sum_{e \in s \setminus s'} c_e(l_e(s)) - \sum_{e \in s' \setminus s} c_e(l_e(s'))$$

- $u_i(s) = \sum_{e \in s \cap s'} c_e(l_e(s)) + \sum_{e \in s \setminus s'} c_e(l_e(s)).$   $u_i(s') = \sum_{e \in s \cap s'} c_e(l_e(s')) + \sum_{e \in s' \setminus s} c_e(l_e(s')).$

Same load

$$\Rightarrow u_i(s) - u_i(s') = \sum_{e \in s \setminus s'} c_e(l_e(s)) - \sum_{e \in s' \setminus s} c_e(l_e(s'))$$

We conclude that  $\Phi(s) - \Phi(s') = u_i(s) - u_i(s')$ .

Proof cont. 
$$\Phi(s) - \Phi(s') = \sum_{e \in s \setminus s'} c_e(l_e(s)) - \sum_{e \in s' \setminus s} c_e(l_e(s'))$$

• 
$$u_i(s) = \sum_{e \in s \cap s'} c_e(l_e(s)) + \sum_{e \in s \setminus s'} c_e(l_e(s)).$$

• 
$$u_i(s) = \sum_{e \in s \cap s'} c_e(l_e(s)) + \sum_{e \in s \setminus s'} c_e(l_e(s)).$$
  
•  $u_i(s') = \sum_{e \in s \cap s'} c_e(l_e(s')) + \sum_{e \in s' \setminus s} c_e(l_e(s')).$ 

Same load

$$\Rightarrow u_i(s) - u_i(s') = \sum_{e \in s \setminus s'} c_e(l_e(s)) - \sum_{e \in s' \setminus s} c_e(l_e(s'))$$

We conclude that 
$$\Phi(s) - \Phi(s') = u_i(s) - u_i(s')$$
.

Remark: Monderer and Shapley showed that potential games can be reduced to congestion games!

# An Algorithm for symmetric network congestion games

Assumption: All players have the same endpoints S and T (and thus they all have the same set of paths/strategies).

Basic idea: Min-cost flow reduction

# An Algorithm for symmetric network congestion games

Assumption: All players have the same endpoints S and T (and thus they all have the same set of paths/strategies).

Basic idea: Min-cost flow reduction

**Definition** (Min-cost flow). Given a graph G(V, E), a source s and a sink t we would like to send flow d from s to t.

 $\min \sum f(u,v) \cdot a(u,v)$ 

• Each edge (u, v) has capacity c(u, v) and cost per flow unit a(u, v).

s.t 
$$f(u,v) \le c(u,v)$$
 for all edges  $(u,v)$  capacity cosntraints  $f(u,v) = -f(v,u)$  for all edges  $(u,v)$  
$$\sum_{w} f(u,w) = 0 \ \forall u \ne s, t \text{ flow conservation}$$
 
$$\sum_{w} f(s,w) = d \text{ and } \sum_{w} f(w,t) = d$$

Intro to AGT

# An Algorithm for symmetric network congestion games

Assumption: All players have the same endpoints S and T (and thus they all have the same set of paths/strategies).

Basic idea: Min-cost flow reduction

**Definition** sink t we u

#### Min-cost flow via LP!

Each

a(u,v).

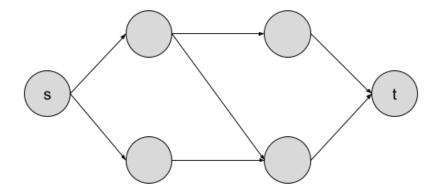
and a

$$\min \sum_{e:(u,v)} f(u,v) \cdot a(u,v)$$

s.t 
$$f(u,v) \le c(u,v)$$
 for all edges  $(u,v)$  capacity cosntraints  $f(u,v) = -f(v,u)$  for all edges  $(u,v)$  
$$\sum_{w} f(u,w) = 0 \ \forall u \ne s, t \text{ flow conservation}$$
 
$$\sum_{w} f(s,w) = d \text{ and } \sum_{w} f(w,t) = d$$

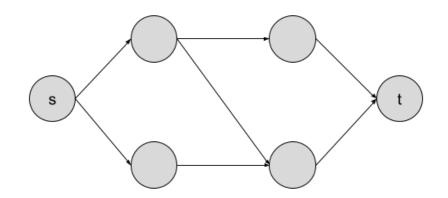
# An Algorithm for symmetric network congestion games; the reduction

Initial graph in the Congestion Game.

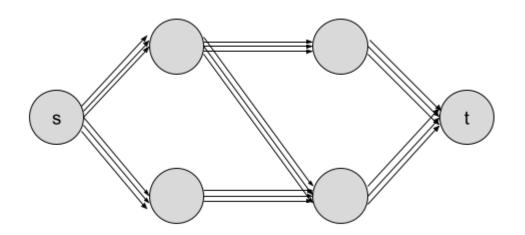


# An Algorithm for symmetric network congestion games; the reduction

Initial graph in the Congestion Game.

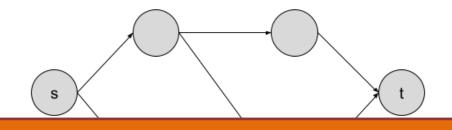


Create another graph with same vertices and for each edge e := (u, v) add n parallel edges of capacity one and costs in increasing order  $c_e(1), ..., c_e(n)$ 



# An Algorithm for symmetric network congestion games; the reduction

Initial graph in the Congestion Game.



The min-cost flow minimizes the potential  $\Phi$ ! HW2

Create another graph with same vertices and for each edge e := (u, v) add n parallel edges of capacity one and costs in increasing order  $c_e(1), ..., c_e(n)$ 

