L07(part b) Min-max Optimization: Local Nash and Last iterate convergence

50.579 Optimization for Machine Learning Ioannis Panageas ISTD, SUTD

- Previously we motivated the Last iterate convergence.
- We show that Gradient Descent Ascent (GDA) diverges even for $x^T A y$.

Intuition: Given the bilinear problem below let's run the continuous GDA.

$$\min_{x \in \mathbb{R}^n} \max_{y \in \mathbb{R}^m} x^T A y.$$

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Recall GDA:

$$\begin{aligned} x_{t+1} &= x_t - \eta \nabla_x f(x_t, y_t), \\ y_{t+1} &= y_t + \eta \nabla_y f(x_t, y_t). \end{aligned}$$

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Lemma (Cycles). It holds that $||x||_2^2 + ||y||_2^2$ is constant w.r.t t.

Proof. It suffices to prove

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Observe that

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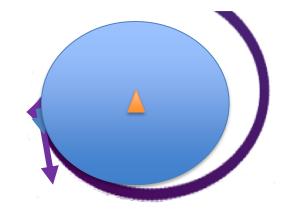
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Hence

$$\frac{d}{dt}\{\|x\|_2^2 + \|y\|_2^2\} = -2\eta x^T A y + 2\eta x^T A y = 0.$$



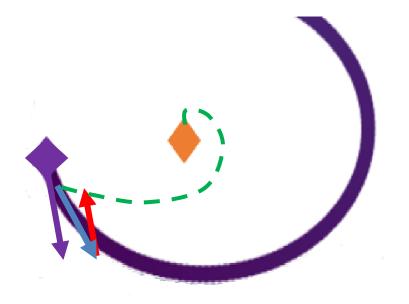
• Question: Can we fix this behavior? We can use "optimism" (negative momentum).

$$\begin{aligned} x_{t+1} &= x_t - \eta \cdot \nabla_x f(x_t, y_t) \\ &+ \eta/2 \cdot \nabla_x f(x_{t-1}, y_{t-1}) \end{aligned}$$
$$\begin{aligned} y_{t+1} &= y_t + \eta \cdot \nabla_y f(x_t, y_t) \\ &- \eta/2 \cdot \nabla_y f(x_{t-1}, y_{t-1}) \end{aligned}$$

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Theorem (Convergence). Consider the bilinear game $x^T A y$ where A is full rank. Optimistic GDA converges pointwise and reaches an ϵ neighborhood in

$$T := \Theta\left(\frac{\lambda_{\max}(AA^T)}{\lambda_{\min}(AA^T)}\log\frac{1}{\epsilon}\right)$$

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The idea behind the proof is to analyze the following dynamical system

$$\begin{pmatrix} x_{t+1} \\ y_{t+1} \end{pmatrix} = \begin{pmatrix} I - \begin{pmatrix} 0 & 2\eta A \\ -2\eta A^T & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} x_t \\ y_t \end{pmatrix} + \eta \begin{pmatrix} 0 & 2\eta A \\ -2\eta A^T & 0 \end{pmatrix} \begin{pmatrix} x_{t-1} \\ y_{t-1} \end{pmatrix}$$

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Let's make it linear system!

Consider the linear dynamical system

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Observe that

$$\begin{pmatrix} x_{t+1} \\ y_{t+1} \\ x_t \\ y_t \end{pmatrix} = \begin{pmatrix} I & -2\eta A & 0 & \eta A \\ 2\eta A^T & I & -\eta A^T & 0 \\ I & 0 & 0 & 0 \\ 0 & I & 0 & 0 \end{pmatrix} \begin{pmatrix} x_t \\ y_t \\ x_{t-1} \\ y_{t-1} \end{pmatrix}$$

Lemma (Eigenvalues). *The matrix above has eigenvalues that are less than one for the appropriate choice of* η *.*

Min-max in bilinear (constrained)

Consider the problem

$$\min_{x \in \Delta_n} \max_{y \in \Delta_m} x^T A y.$$

Projected Optimistic GDA not clear if works... Let's do Optimistic MWU!

$$\begin{split} x_i^{t+1} &= x_i^t \frac{1 + 2\eta (Ay^t)_i - \eta (Ay^{t-1})_i}{\sum_j x_j^t (1 + 2\eta (Ay^t)_j - \eta (Ay^{t-1})_j)}, \\ y_i^{t+1} &= y_i^t \frac{1 - 2\eta (A^\top x^t)_i + \eta (A^\top x^{t-1})_i}{\sum_j y_j^t (1 - 2\eta (A^\top x^t)_j + \eta (A^\top x^{t-1})_j)}. \end{split}$$

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Theorem (Convergence). Let A be the payoff matrix of a zero sum game and the game has a unique Nash equilibrium. It holds that for η sufficiently small (depends on n, m, A, η can be exponentially small in n, m), starting from uniform distribution $\lim_{t\to\infty} (x^t, y^t) = (x^*, y^*)$ under OMWU dynamics

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Definition (Local Nash). A critical point x^*, y^*) is a local Nash if there exists a neighborhood U around (x^*, y^*) so that for all $(x, y) \in U$ we have that

$$f(x^*, y) \le f(x^*, y^*) \le f(x, y^*).$$

• Does there always exist a local Nash? Is it a good solution concept?

• Min-max theorem is not applicable. How can we solve such a problem?

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Theorem (Local Convergence). Under some mild assumptions on f(x, y) and stepsize we have

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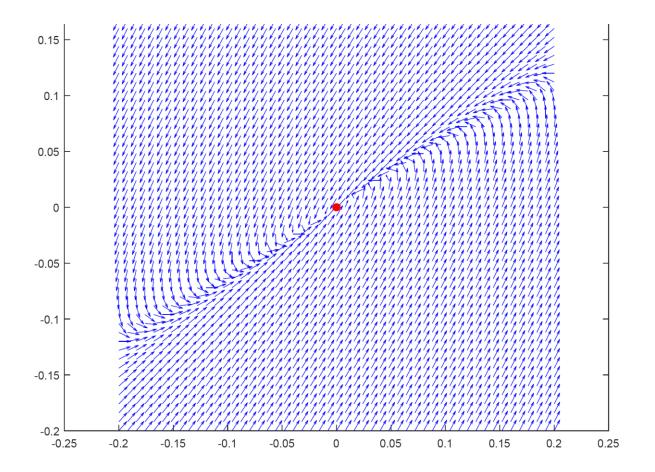
Lemma (Inclusion strict). There are functions with critical points that are GDAstable but not local Nash. An example is $f(x,y) = -\frac{1}{8}x^2 - \frac{1}{2}y^2 + \frac{6}{10}xy$.

Proof. Let $f(x,y) = -\frac{1}{8}x^2 - \frac{1}{2}y^2 + \frac{6}{10}xy$. Computing the Jacobian of the update rule of OGDA at (0,0) we get

$$J_{\text{GDA}} = \begin{pmatrix} 1 + \frac{1}{4}\eta & -\frac{6}{10}\eta \\ \frac{6}{10}\eta & 1 - \eta \end{pmatrix}$$

Both eigenvalues of J_{GDA} have magnitude less than 1 (for any $0 < \alpha < 1.34$). GDA is contracting around (0, 0).

However it is clear that (0,0) is not a local Nash. Why?



Conclusion

- Introduction to min-max optimization.
 - Negative momentum for last iterate convergence.
 - Bilinear unconstrained and constrained
 - Local Nash
- Next lecture we will talk about PAC learning and ERM.