# L06 Online Learning and a proof of Minimax Theorem

CS 280 Algorithmic Game Theory Ioannis Panageas

**Definition.** For each day t = 1...T, you have to choose between alternatives A, B (e.g., rain or not rain).

- Choose A or B according to some rule.
- One of the alternatives realizes.
- *If you choose correctly you are not penalized otherwise you lose one point.*
- Imagine that there are n experts who on each day t, recommend either A or B.

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Can you be correct all the time? What is the "right" objective?

Perform close to best expert!

**Algorithm** (Weighted Majority). *We define the following algorithm:* 

- 1. Initialize  $w_i^0 = 1$  for all  $i \in [n]$ .
- 2. For  $t=1 \dots T$  do

3. If 
$$\sum_{i \text{ choose } A} w_i^{t-1} \ge \sum_{i \text{ choose } B} w_i^{t-1}$$

- 4. Choose A, otherwise B.
- 5. **End If**
- 6. For expert i that made a mistake **do**

7. 
$$w_i^t = (1 - \epsilon) w_i^{t-1}$$
.

- 8. End For
- 9. For expert i that did not make a mistake **do**
- 10.  $w_i^t = w_i^{t-1}$ .
- 11. End For
- 12. End For

Remarks:

- *ϵ* is the stepsize (to be chosen later).
- Performs almost as good as ``best" expert (fewest mistakes)

**Theorem (Weighted Majority).** Let  $M_T$ ,  $M_T^B$  be the total number of mistakes the algorithm and best expert make until step T, respectively. It holds that

$$M_T \leq \mathbf{2}(1+\epsilon)M_T^B + \frac{\log n}{\epsilon}$$

*Proof.* Let's define the potential function  $\phi_t = \sum_i w_i^t$ .

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- $\phi_{t+1} \leq \phi_t \text{ (why?)}.$

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- $\phi_0 = n$ .
- $\phi_{t+1} \leq \phi_t$  (why?).

Observe that if we make a mistake at time t then the majority was wrong, that is at least  $\frac{\phi_t}{2}$  will be multiplied by  $(1 - \epsilon)$ .

Hence, if we make a mistake then  $\phi_{t+1} \leq (1-\epsilon)\frac{\phi_t}{2} + \frac{\phi_t}{2} = (1-\frac{\epsilon}{2})\phi_t$ 

**Theorem (Weighted Majority).** Let  $M_T$ ,  $M_T^B$  be the total number of mistakes the algorithm and best expert make until step T, respectively. It holds that

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Proof. Let's That is  $\phi_{t+1} \leq (1-\frac{\epsilon}{2})\phi_t$  when we do a mistake, otherwise just  $\phi_{t+1} \leq \phi_t$ . Since we have  $M_T$  mistakes, then
 $\phi_t$ 
 $\phi_t = \phi_t \left(1-\frac{\epsilon}{2}\right)^{M_T} \phi_1.$ 
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*Proof cont.* Moreover, assuming the best expert (say  $i^*$ ) did  $M_T^B$  mistakes, we have

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We conclude that

$$(1-\epsilon)^{M_T^B} < \left(1-\frac{\epsilon}{2}\right)^{M_T} n.$$

By taking the log,  $M_T^B \log(1-\epsilon) < \log(1-\epsilon/2)M_T + \log n$ .

*Proof cont.* Moreover, assuming the best expert (say  $i^*$ ) did  $M_T^B$  mistakes, we have

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Since 
$$-x - x^2 < \log(1 - x) < -x$$
,  $M_T^B(-\epsilon - \epsilon^2) < -M_T\epsilon/2 + \log n$ .

# The general setting

**Definition.** At each time step t = 1...T.

- *Player* chooses  $x_t \in \Delta_n$ .
- Adversary chooses  $u_t \in [-1,1]^n$ .
- *Player* gets payoff  $x_t^{\top} u_t$  and observes  $u_t$ .

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Player's goal is to minimize the (time average) Regret, that is:

$$\frac{1}{T} \left[ \max_{x \in \Delta_n} \sum_{t=1}^T x^\top u_t - \sum_{t=1}^T x_t^\top u_t \right].$$
$$= \frac{1}{T} \left[ \max_{i^* \in [n]} \sum_{t=1}^T x^\top u_{t,i} - \sum_{t=1}^T x_t^\top u_t \right].$$

If Regret  $\rightarrow 0$  as T  $\rightarrow \infty$ , the algorithm is called **no-regret**.

**Algorithm** (MWU). *We define the following algorithm:* 

- 1. Initialize  $p_i^0 = \frac{1}{n}$  for all  $i \in [n]$ .
- 2. For  $t=1 \dots T$  do
- 3. For each *i* that gives payoff  $u_{t,i}$  do
- 4.  $p_i^{t+1} = p_i^t \frac{1 + \epsilon u_{t,i}}{Z^t}.$
- 5. End For
- 6. End For

Remarks:

- $\epsilon$  is the stepsize (to be chosen later).
- Performs almost as good as ``best" expert (fewest mistakes).
- The algorithm is also called Multiplicative Weights Update!
- $Z^t = \sum_i p_i^t (1 + \varepsilon u_{t,i})$  is renormalization constant.

**Theorem** (MWU). It holds that

$$rac{1}{T}\sum_t u_t^ op p^t \geq \max_x \sum_t x^ op u_t - rac{\log n}{\epsilon T} - \epsilon.$$

*Proof.* Let's define the potential function  $\phi_t = \sum_i w_i^t$  where  $w_i^t = \prod_{s=0}^t (1 + \epsilon u_{s,i}).$ 

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Let the best strategy be  $i^*$ , we have

$$\phi_T > w_{i^*}^T \ge e^{\epsilon \sum_{s=0}^T u_{s,i^*} - \epsilon^2 \sum_{s=0}^T u_{s,i^*}^2}.$$

Now 
$$\phi_{t+1} = \sum w_i^{t+1} = \sum w_i^t (1 + \epsilon u_{t,i})$$

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*Proof cont.* Therefore

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$$\leq \phi_t e^{\epsilon \sum_i p_i^t u_{i,t}} = \phi_t e^{\epsilon u_t^\top p^t}$$

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Telescopic product gives

$$\phi_T \le \phi_0 e^{\epsilon \sum_t u_t^\top p^t} = n e^{\epsilon \sum_t u_t^\top p^t}.$$

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Therefore  $e^{\epsilon \sum_{s=0}^{T} u_{s,i^*} - \epsilon^2 \sum_{s=0}^{T} u_{s,i^*}^2} \leq n e^{\epsilon \sum_t u_t^\top p^t}$ , or equivalently  $\epsilon OPT - \epsilon^2 T \leq \epsilon OPT - \epsilon^2 \sum_{s=0}^{T} u_{s,i^*}^2 \leq \log n + \epsilon \sum_t u_t^\top p^t.$ 

Intro to AGT

*Proof cont.* Therefore

Set 
$$\varepsilon \to \sqrt{\frac{\ln n}{T}}$$
 and we get regret  
2  $\sqrt{\frac{\ln n}{T}}$  (No-regret!)

Telescopic product gives  

$$\phi_T \leq \phi_0 e^{\epsilon \sum_t u_t^\top p^t} = n e^{\epsilon \sum_t u_t^\top p^t}.$$

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**Theorem** (Minimax by John von Neumann). *Let* A *a matrix of size*  $n \times m$ .

$$\min_{x \in \Delta_n} \max_{y \in \Delta_m} x^{ op} A y = \max_{y \in \Delta_m} \min_{x \in \Delta_n} x^{ op} A y$$

Remarks

- The above is the value of the game.
- Note that It is always true (min-max inequality):

 $\inf_{x \in \mathcal{X}} \sup_{y \in \mathcal{Y}} f(x, y) \ge \sup_{y \in \mathcal{Y}} \inf_{x \in \mathcal{X}} f(x, y)$ 

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- The above is the value of the game.
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$$\begin{split} \inf_{x \in \mathcal{X}} \sup_{y \in \mathcal{Y}} f(x, y) \geq \sup_{y \in \mathcal{Y}} \operatorname{ir} \overset{\text{Define } g(z) \triangleq \inf_{w \in W} f(z, w).}{\forall w, \forall z, g(z) \leq f(z, w)} \\ \Rightarrow \forall w, \sup_{z} g(z) \leq \sup_{z} f(z, w) \\ \Rightarrow \sup_{z} g(z) \leq \inf_{w} \sup_{z} f(z, w) \\ \Rightarrow \sup_{z} \inf_{w} f(z, w) \leq \inf_{w} \sup_{z} f(z, w) \end{split}$$

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*Proof.* Let's use no-regret learning for both "players"!

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$$\min_{x \in \Delta_n} \max_{y \in \Delta_m} x^\top A y = \max_{y \in \Delta_m} \min_{x \in \Delta_n} x^\top A y$$

Proof. Let's use no-regret learning for both "players"!

Let  $x_1, ..., x_T$  and  $y_1, ..., y_T$  be the iterates as advised by MWU and define  $\hat{x} = \frac{1}{T} \sum_{i=1}^{T} x_i$  and  $\hat{y} = \frac{1}{T} \sum_{i=1}^{T} y_i$  and  $T = \Theta(\frac{1}{\eta^2})$ .

Choose any x, then from the no-regret property for x we get that

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$$\frac{1}{T} \sum_{t} x_{t}^{\top} A y_{t} \leq \frac{1}{T} \sum_{t} x^{\top} A y_{t} + \eta$$
$$= x^{\top} A \left( \frac{\sum_{t} y_{t}}{T} \right) + \eta.$$

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Proof cont.

Choose any y, then from the no-regret property for y we get that

$$\frac{1}{T} \sum_{t} x_{t}^{\top} A y_{t} \geq \frac{1}{T} \sum_{t} x_{t}^{\top} A y - \eta$$
$$= \left(\frac{\sum x_{t}}{T}\right)^{\top} A y - \eta.$$

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We conclude that for all x, y we have

$$\left(\frac{\sum x_t}{T}\right)^\top Ay \ - \ 2\eta \le x^\top A \left(\frac{\sum_t y_t}{T}\right).$$

Proof cont.

Choose any y, then from the no-regret property for y we get that

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$$\max_{\boldsymbol{y}} \left(\frac{\sum x_t}{T}\right)^\top A \boldsymbol{y} \ - \ 2\eta \leq \min_{\boldsymbol{x}} \boldsymbol{x}^\top A \left(\frac{\sum_t y_t}{T}\right).$$

Finally we get 
$$\max_{y} \min_{x} x^{\top} A y \ge \min_{x} x^{\top} A \left(\frac{\sum_{y} y_{t}}{T}\right)$$

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Proof cont.

Choose an

Set  $\eta 
ightarrow 0$  and we are done!

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We conclude that for all x, y we have

$$\max_{y} \left(\frac{\sum x_{t}}{T}\right)^{\top} Ay - 2\eta \leq \min_{x} x^{\top} A\left(\frac{\sum_{t} y_{t}}{T}\right).$$

Finally we get 
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